

Embedded Networks

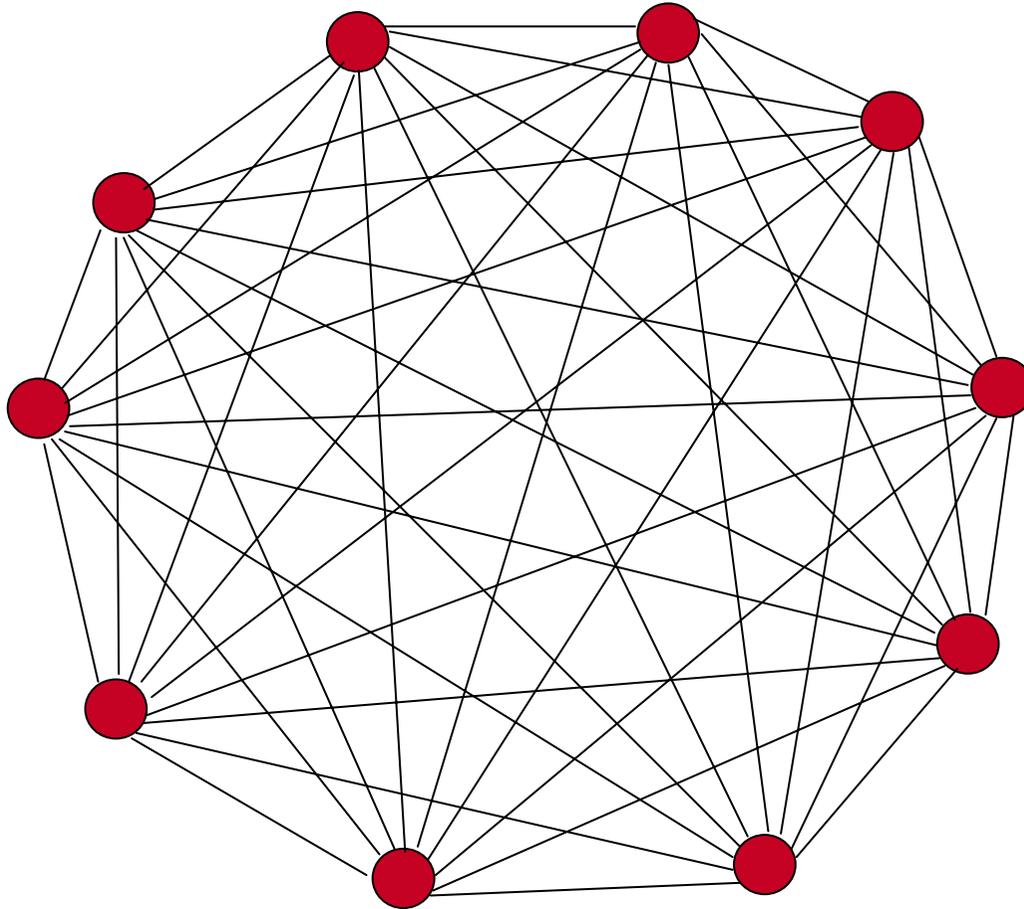
Models of Communication

Summer Term 2007



Interaction Structure in Co-operative Systems

many-
to-
many



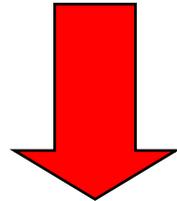
manageability

goal  **sharing information and co-ordinating activities**



CO-OPERATIVE SYSTEMS

Which model of communication?



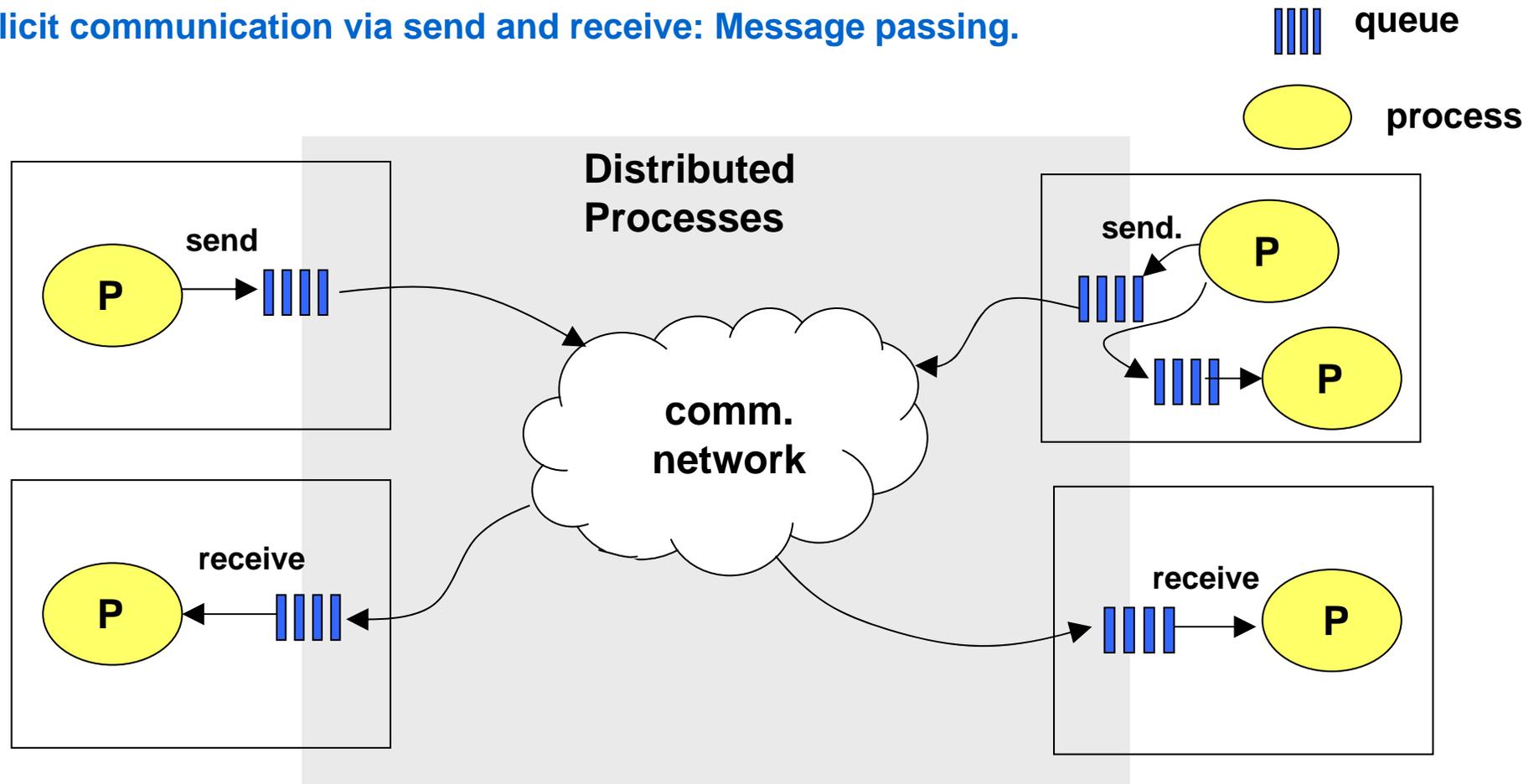
What kind of addressing and routing should be supported by the network?

Which abstractions in the programming model?



Message Passing

Explicit communication via send and receive: Message passing.

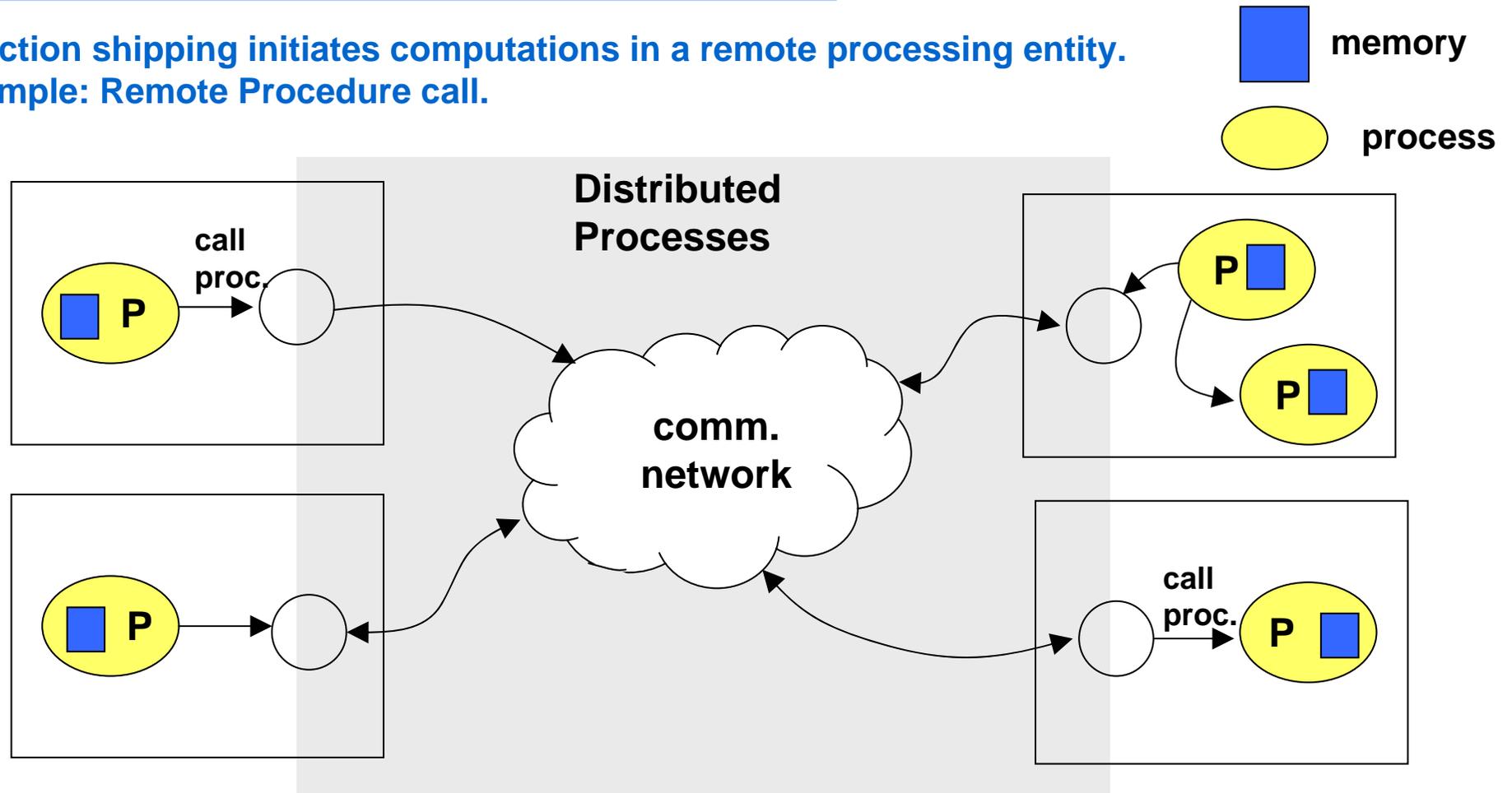


Problem: very low level, very general, poorly defined semantics of communication



Remote Procedure Call

Function shipping initiates computations in a remote processing entity.
Example: Remote Procedure call.

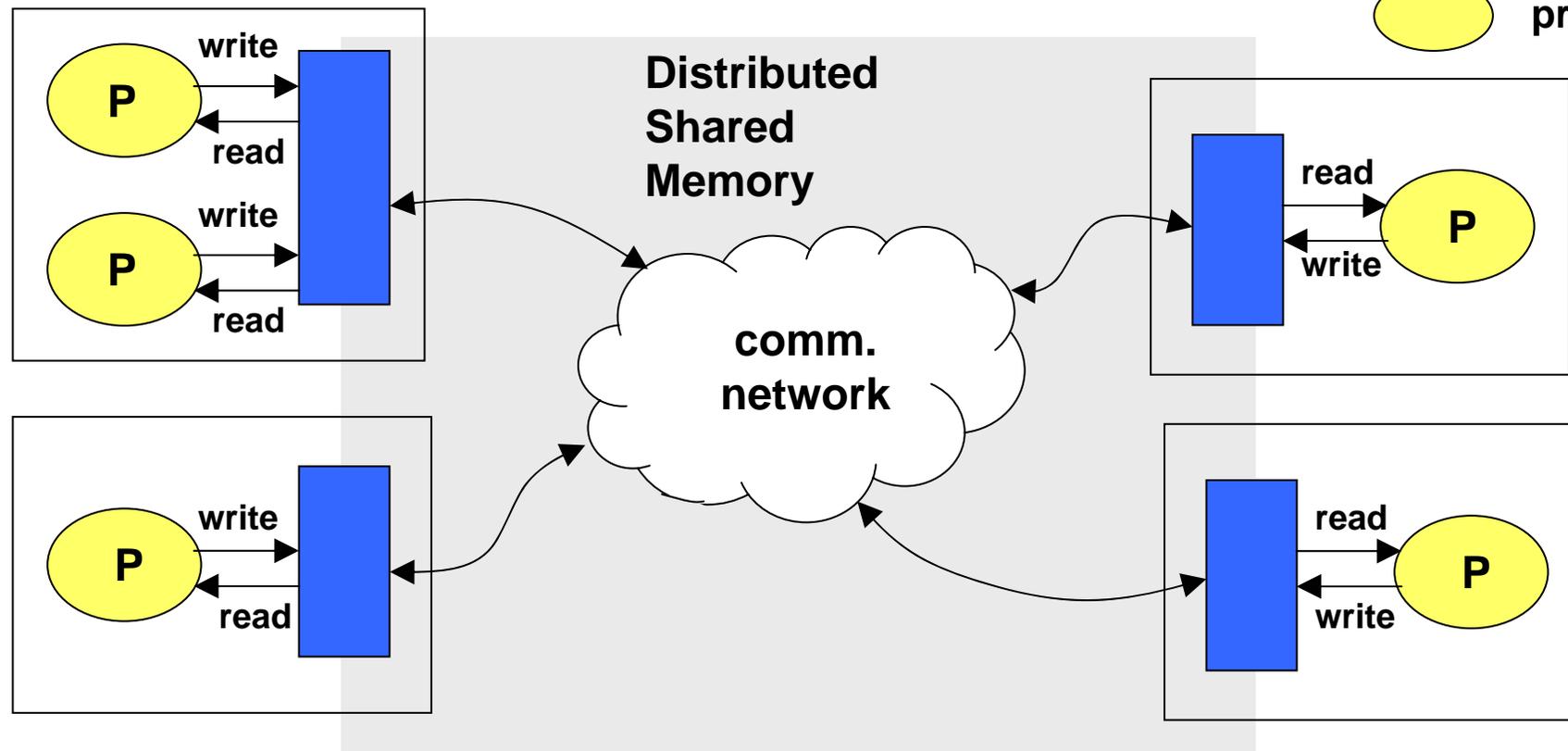
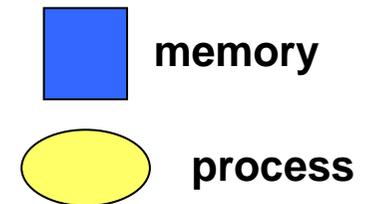


Problem: computation bottlenecks, more complex programming model, references.



Distributed Shared memory

DSM (Data shipping) maintains the read/write semantics of memory



Problem: Consistency in the presence of concurrency and communication delays



Abstractions for Communication

- ➔ **Message passing**
- ➔ **Remote Procedure Call**
- ➔ **Remote Object Invocation**
- ➔ **Distributed shared memory**
- ➔ **Notifications**
- ➔ **Publish Subscribe**
- ➔ **Shared data spaces**



Abstractions for Communication

Dimensions of Dependencies:

Flow coupling: Control transfer with communication

Defines whether there is a control transfer coupled with a message transfer.
E.g. if the sender blocks until a message is correctly received.

Space Coupling: References must be known

Explicit specification of the destination, i.e. producer must know where to send the message. Message contains an ID specifying an address or name.

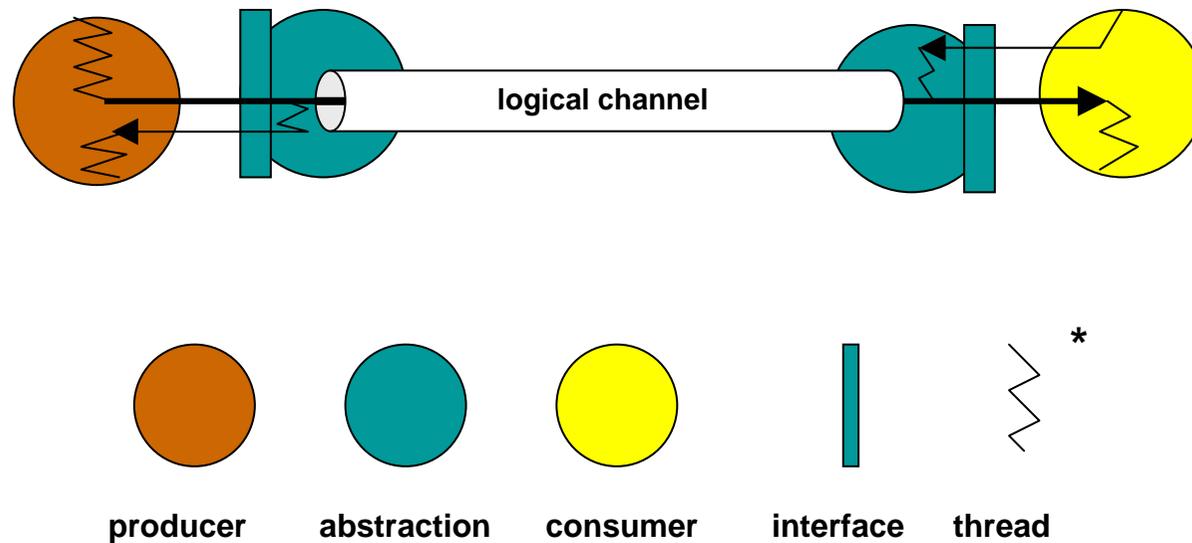
Coupling in time: Both sides must be active

Communication can only take place if all partners are up and active.



Message passing

Connected socket, e.g. TCP



primitives: `send ()`, `receive ()`

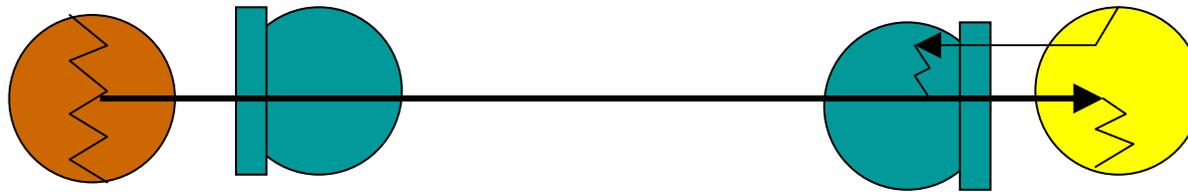
Coupling: flow, space, time

* Notation acc. P. Eugster: Type-Based Publish Subscribe, PhD-thesis, EPFL, Nr. 2503, 2001



Message passing

Unconnected socket, e.g. UDP



primitives: `send ()`, `receive ()`

Coupling: (flow? unsuccessful if flow is not coordinated), space, time



Remote Procedure Call (RPC)



Relation: one-to-one

Coupling:

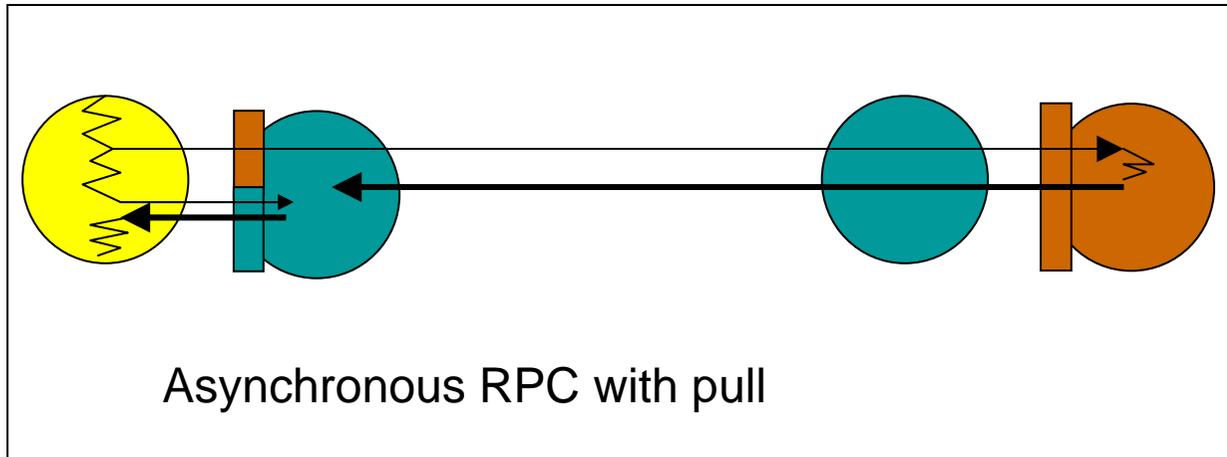
Space: destination is explicitly specified

Flow: blocks until message is delivered

Time: both sides must be active



Variations of RPC



Example: Concurrent Smalltalk

Relation: one-to-one

Coupling:

Space:

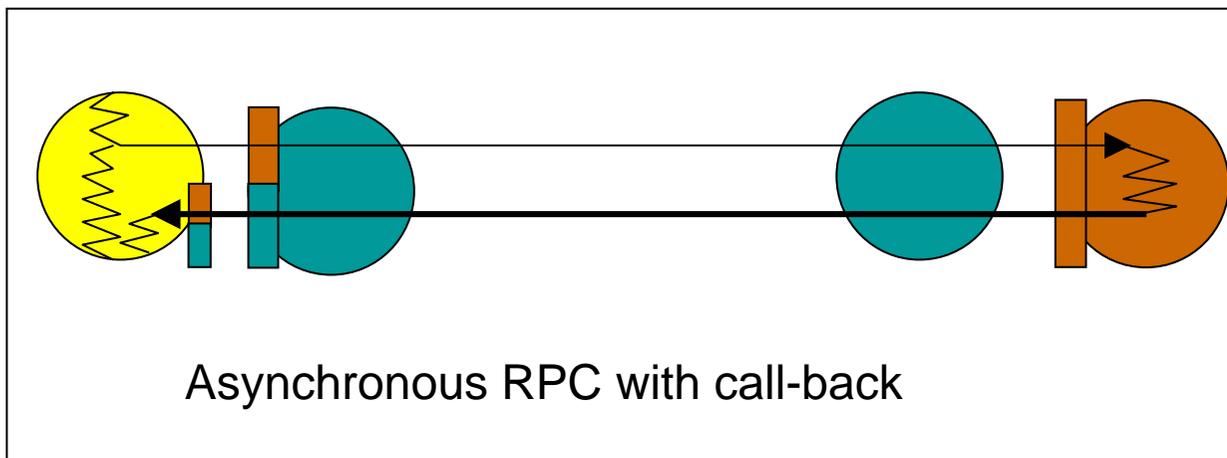
destination is explicitly specified

Flow:

no flow coupling

Time:

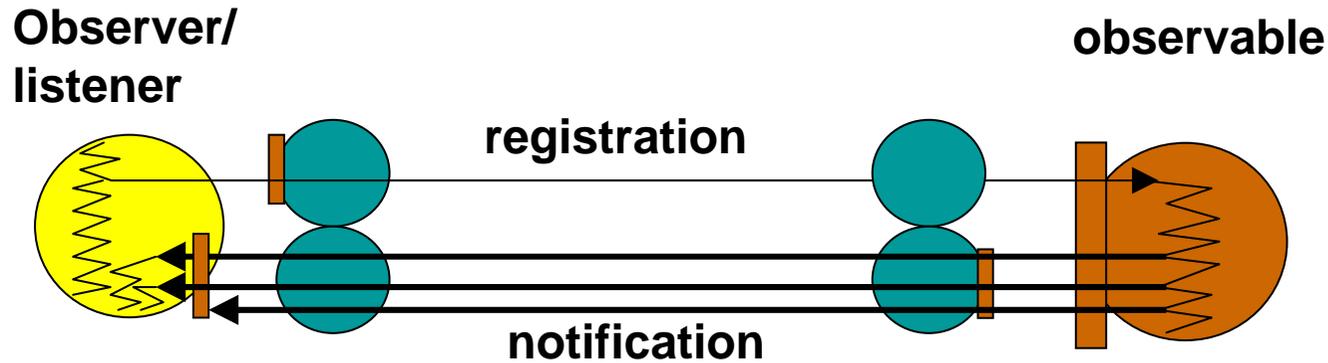
both sides must be active



Example: Eiffel



Notification



Examples:
Java

Relation: one-to-many

Coupling:

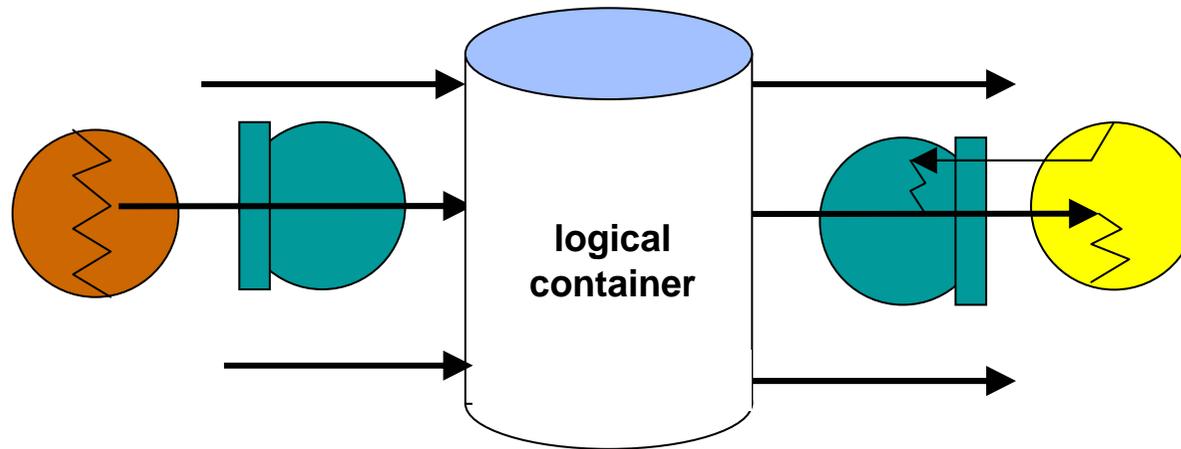
Space: Yes (Observable/Observer pattern (delegation))

Flow: none

Time: both sides must be active (notification performed by RMI)



Shared Data Spaces



Relation: many-to-many

Coupling:

Space: none

Flow: consumer side

Time: none

Examples:

Linda Tuple Space

Java Spaces

ADS Data field



Shared Data Spaces

Processes communicate via the "Tuple" Space,
A tuple is only data, non address, no identifier,
A tuple is a data structure similar to a struct in C,

Examples: ("3numbers", 3, 6, 7), ("matrix" , 1, 5, 3.23, 8),
("faculty", "is_member_of", "franz", "maria", "otto")

Primitives (operations) in Linda:

op. in: takes (and removes) an element from the tuple space

op. read: reads an element from the tuple space

op. out: puts a tuple into the tuple space

op. eval: allows to evaluate the fields of a tuple, results are put in the tuple space [example: ("product", mult(4,7))]

No Tuple is ever (over-) written! "out" always put a new item in the space.



Shared Data Spaces

Content-Based Addressing by Tuple matching:

All fields in a template are compared to all tuples.

A match of a template occurs if:

- tuple has the same number of fields
- AND types of fields are equivalent
- AND contents corresponds

Example:

<"distance_sensor", "N", 23>

<"distance_sensor", "E", 127>

<"distance_sensor", "S", 127>

<"distance_sensor", "W", 12>

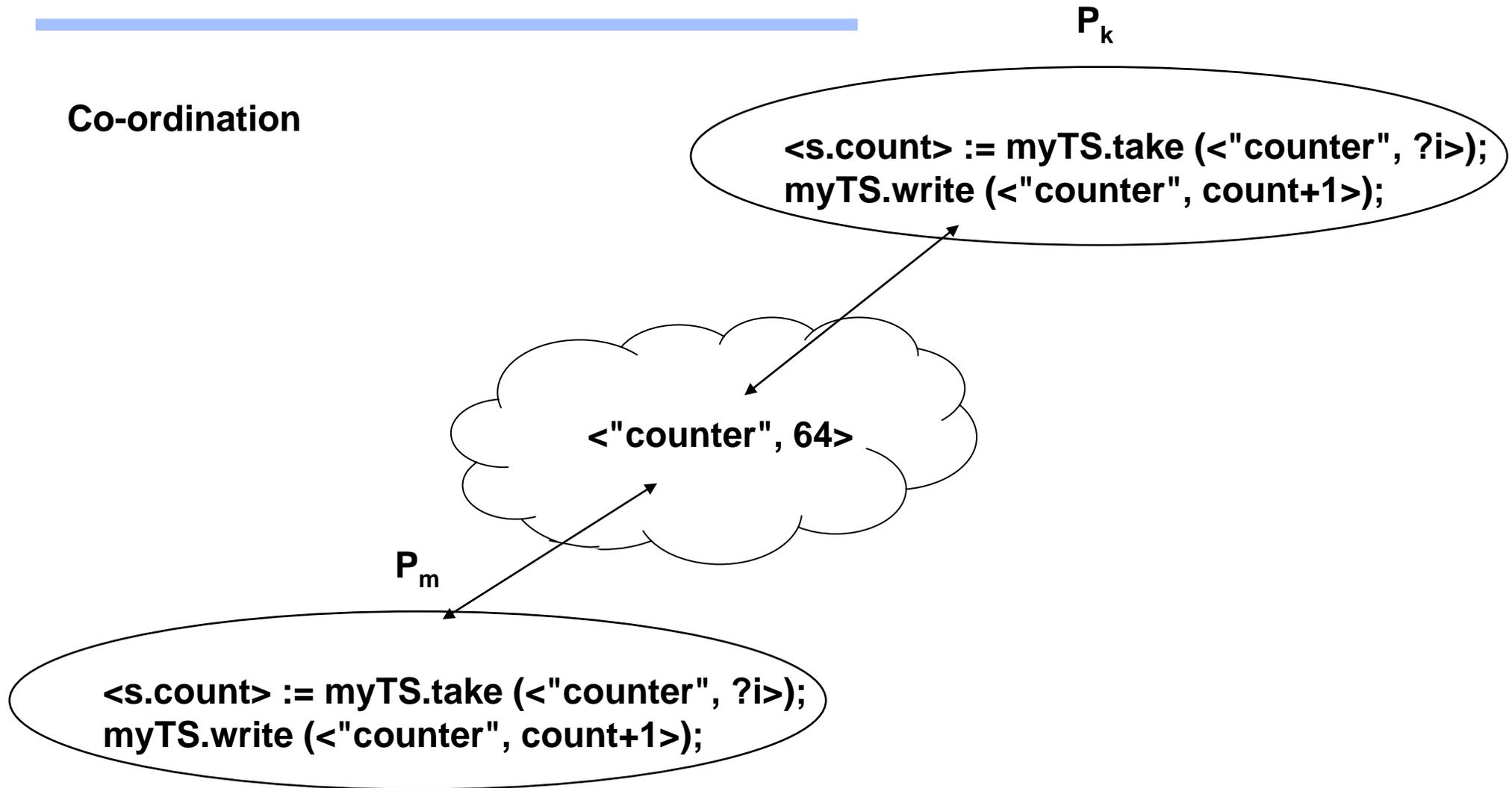
in(<"distance_sensor", " ", ?i> : reads all distance sensors and removes their values from the space.

read(<"distance_sensor", S, ?i>: subsequent read blocks until new S-value has been put to the Space.



Shared Data Spaces

Co-ordination



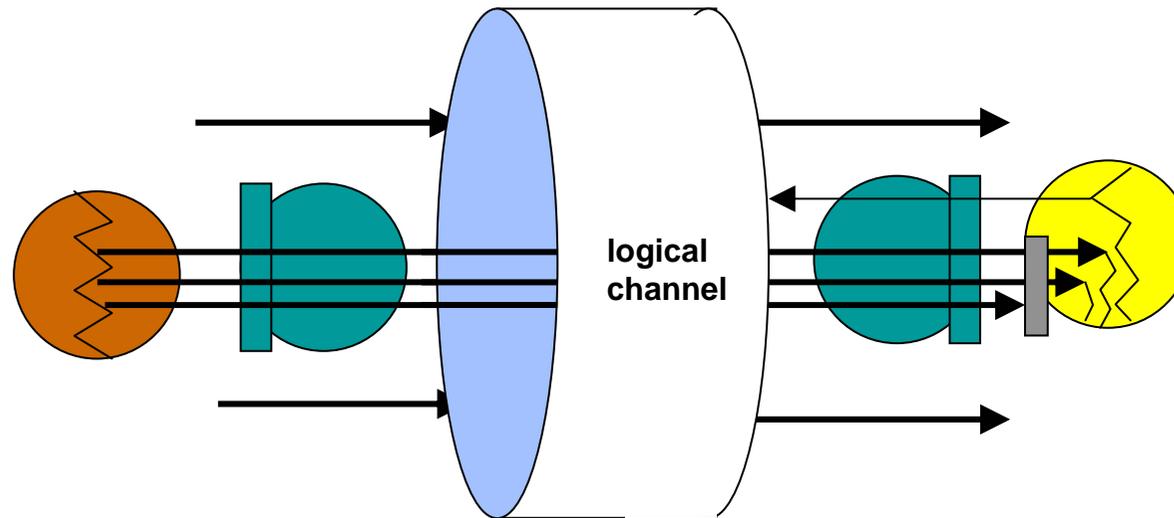
Shared Data Spaces

Immutable Data Storage:

- ➔ no write operation!
- ➔ "out" always adds a data element to the storage
- ➔ destructive "in" and non-destructive "read"
- ➔ consistency is preserved by ordering accesses
- ➔ examples: Linda, JavaSpaces



Publish/Subscribe



Relation: many-to-many

Coupling:

Space: none

Flow: none

Time: none

Examples:

Information Bus

NDDS

Real-Time P/S

COSMIC

....

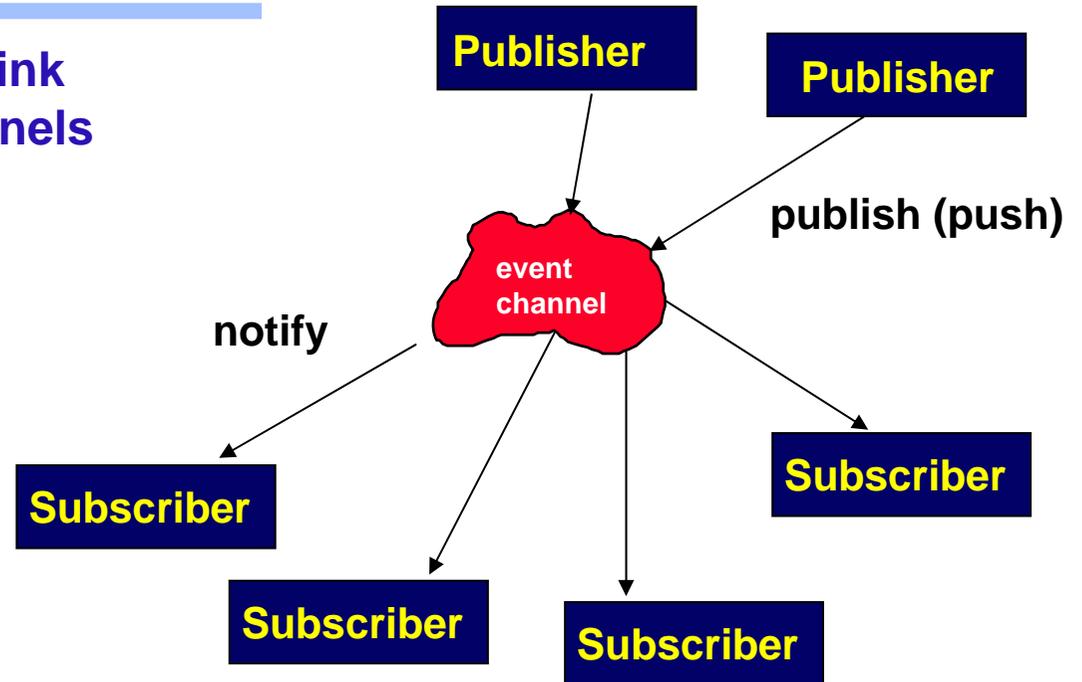
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The Publisher/Subscriber Model

Principle: Keep control local and link systems via event channels

- Information Bus** (*Oki, Pfluegl, Siegel, Skeen*)
- iBus** (*Maffeis*)
- Real-Time P/S** (*Rajkumar, Gagliardi, Sha*)
- NDDS** (*Real-Time Innovations, Inc.*)
- SIENA** (*Carzanoga, Rosenblum, Wolf*)
- Directed Diff.** (*Intanagonwiwat, Govindan, Estrin*)



Many-to-many communication

Support for event-based spontaneous (generative) communication

Anonymous communication

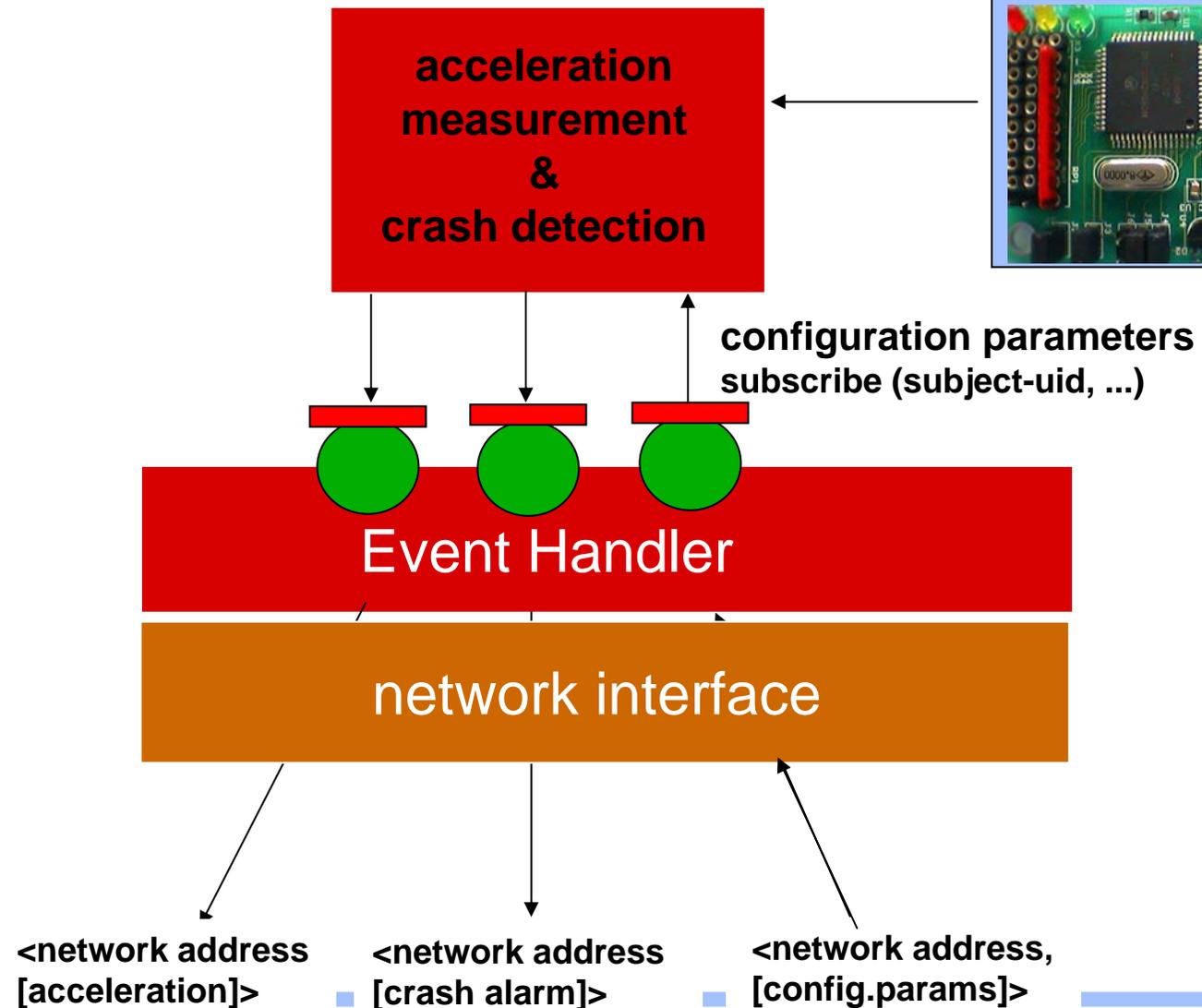
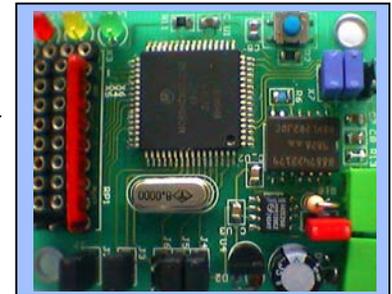


P/S in a smart sensor application

event: acceleration
publish (subject,attr.,
[acceleration]);

event: alarm
publish (subject, attr.,
[alarm]);

acceleration sensor



Overview

Abstraction	Space Coupling	Time Coupling	Flow Coupling
• Connected Sockets	Yes	Yes	Yes
• Unconnected Sockets	Yes	Yes	Consumer
• RPC	Yes	Yes	Consumer
• Oneway RPC	Yes	Yes	No
• async (Pull)	Yes	Yes	No
• async (Callback)	Yes	Yes	No
• Implicit Future	Yes	Yes	No
• Notications (Observer Design Pattern)	Yes	Yes	No
• Tuple Spaces (Pull)	No	No	Consumer
• Message Queues (Pull)	No	No	Consumer
• Subject-Based P/S	No	No	No
• Content-Based P/S	No	No	No



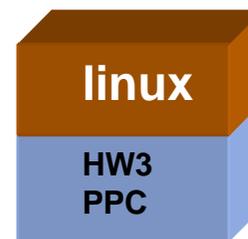
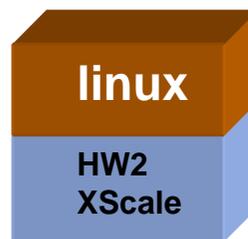
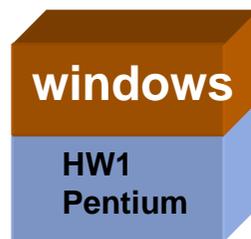
What are the options?

Communication model	Communication abstraction	Communication relation	Routing mechanism	Binding Time
message based	message	symmetric	address	design time
Remote procedure Call	invocation	client-server	address	design time
Distributed shared memory	memory cell	central	address	design time
Shared Data Spaces	object,tupel	central	contents	run time
Publish-Subscribe	event	Producer-consumer	contents/ subject	run time



Distributed system architecture

abstracting
from HW



Distributed system architecture

